

Theory of Efficient Algorithms



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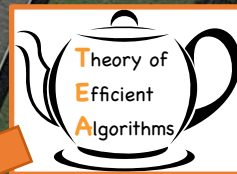
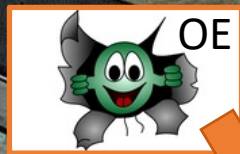
Peter Kling



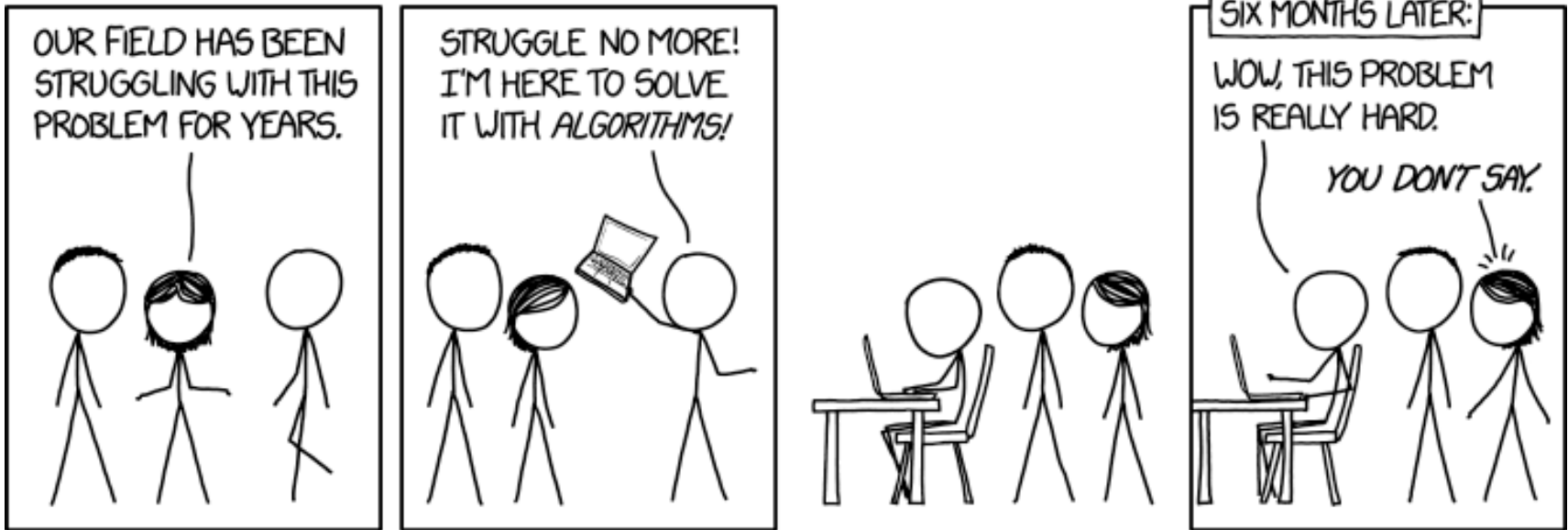
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Focus: Design & Analysis of Algorithms

- Distributed Systems
- Online Computation
- Resource Management
- Stochastic Processes
- Robot Coordination
- ...



Theory of Efficient Algorithms



Why is the problem hard?

How hard is the problem?

What part of the problem is hard?

Can we solve it anyway?

Teaching

Teaching Overview

Winter Term

InfB-AD: Algorithms & Data Structures

Required Basic
Bachelor Course

Summer Term

InfM-MDAE: Methods of Algorithm Design

Wahlpflichtbereich
Theorie

Always

Master's Thesis

talk to me

Methods of Algorithm Design

Module InfM-MDAE

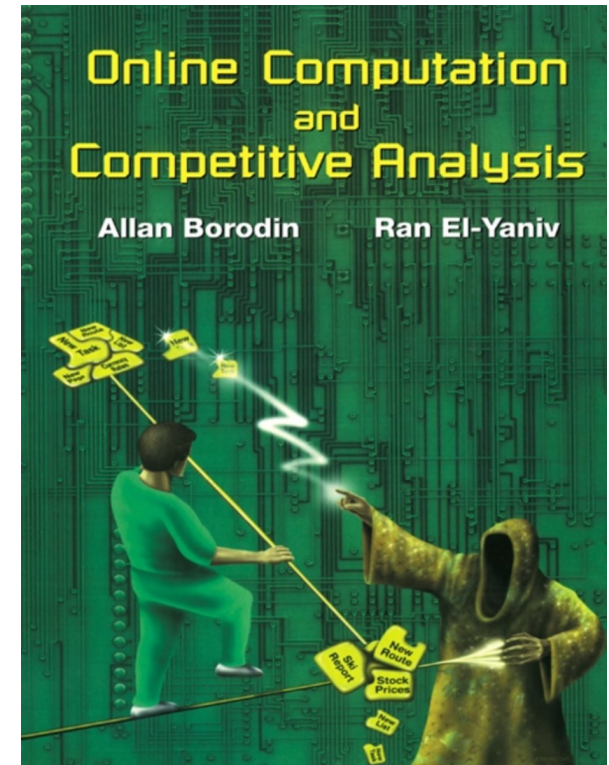
- approximation & online algorithms
- quality guaranties under uncertainty
- how to design & **analyze** optimization algorithms

Lecture

- definitions + theorems + proofs
- (black-/white-) board (+ slides)
- integrated exercises

Seminar

- block seminar with talks and thesis

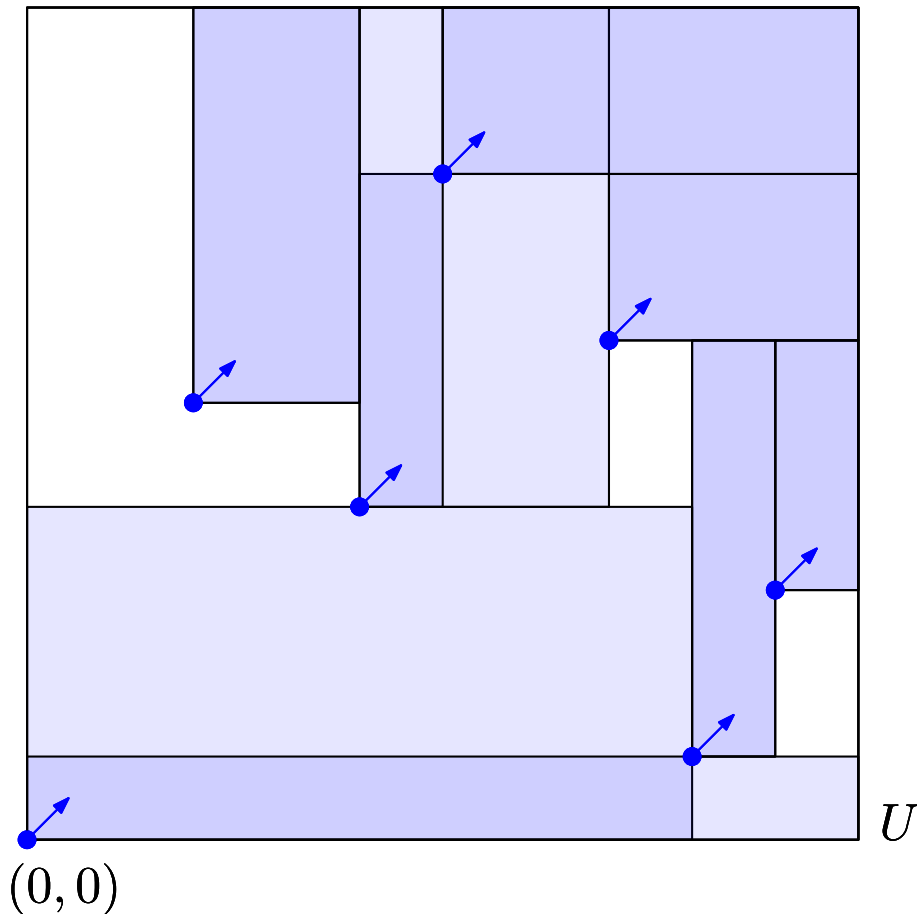


Research Examples

or: some Algorithmic Puzzles

Anchored Rectangle Packing

- n points in the unit square
- one of them at $(0,0)$



Objective

- for each point p , choose an axis-aligned rectangle with lower-left corner at p
- must be non-overlapping
- maximize covered area

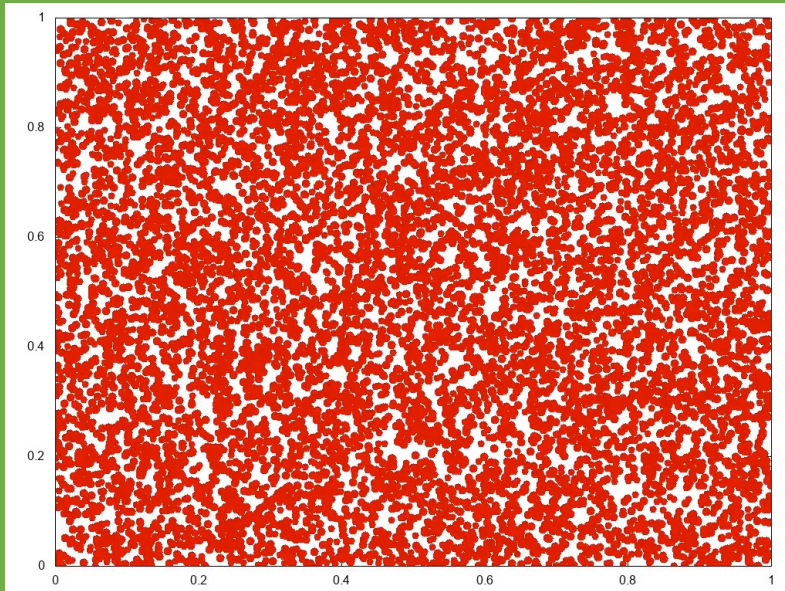
Randomized Gathering

- n robots in the plane
- act in discrete rounds
- instantaneous movement
- not necessarily local

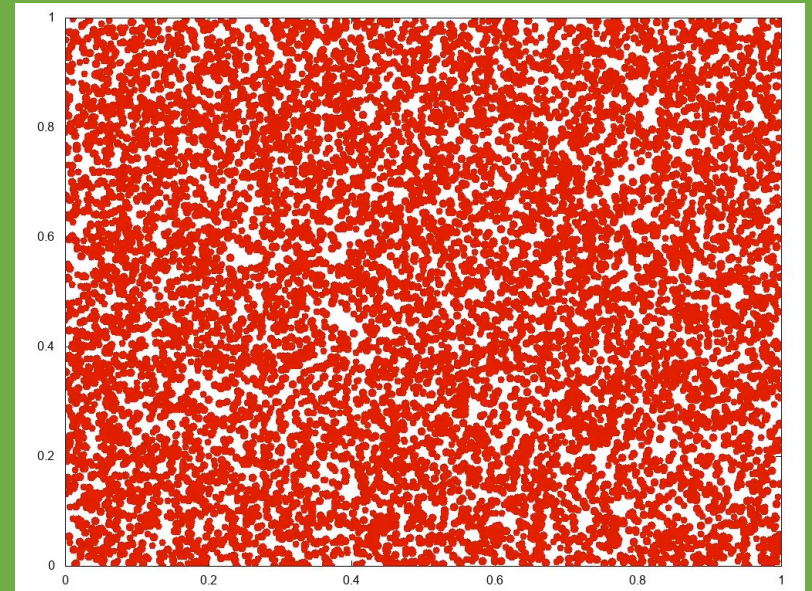
Objective:

Gather in one point

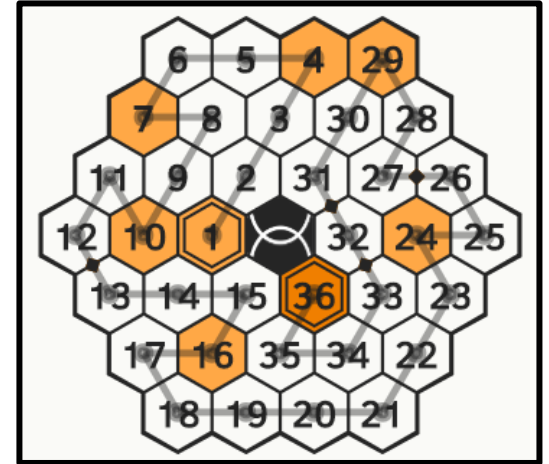
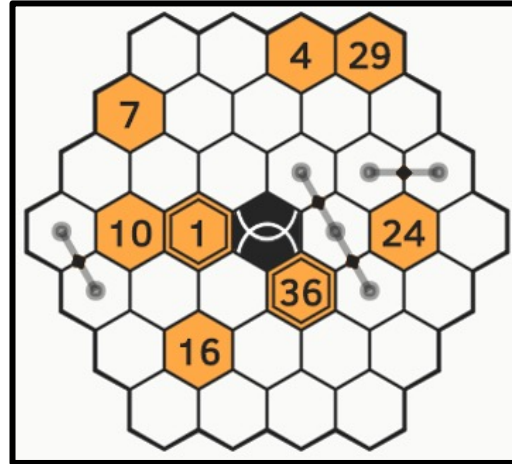
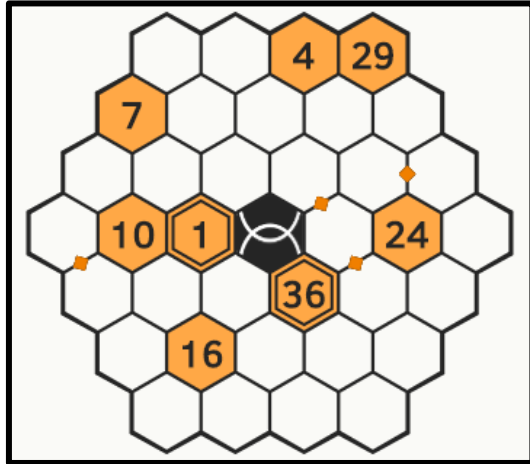
Strategy 1:
go to random robot



Strategy 2:
go to closest of two random robots



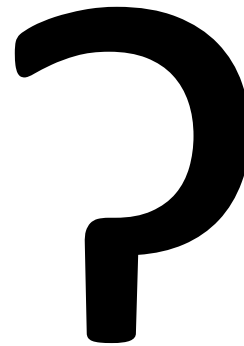
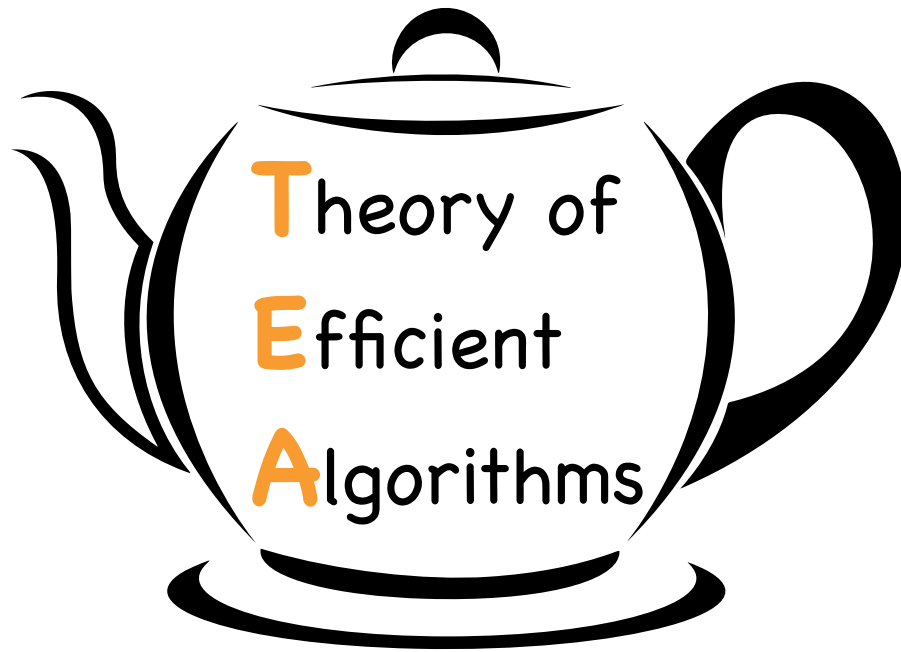
Rikudo



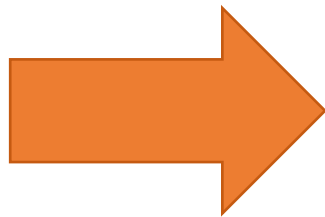
Let's try something simpler: Rikudo on the line

(sort of)





Questions



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